**Deliverables for:**

**KTTD 3B-2021: Integration of Photo-Interpreted and LiDAR Attributes into a Polygonal Forest Inventory Framework**

**Open-Source Code and Project Website:** <https://bermane.github.io/ontario-inventory>

This online tool serves as a project guide that provides the entire coding workflow in the R programming language. It walks through each coding step, providing details about how to run the code, and what the code itself is doing. Results are also generated throughout the online tool and the performance of the segmentation and imputation algorithms is assessed. This tool will help current and future ministry and industry staff to use this technology to integrate forest inventories in the future and across regions.

**Project Video:** <https://ln5.sync.com/dl/593bdff80/ukvyjrdk-xggz3dhv-qzqfw3j7-8h85j46q>

**Research Paper:** Submitted to peer-reviewed journal in April 2023. Currently under review and will be posted when published.